



Eco-Friendly Applications in Connected and Automated Vehicle Technology

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UCR College of Engineering- Center for Environmental Research & Technology









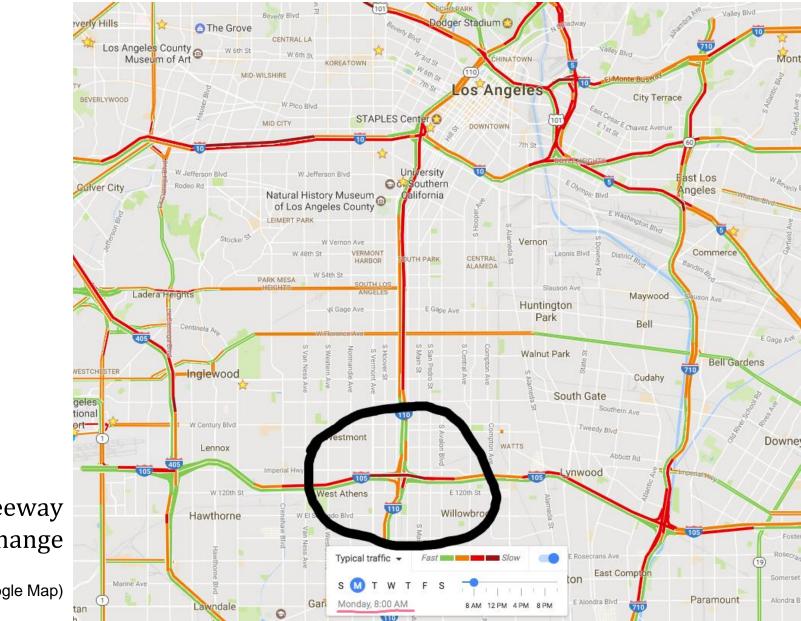


105/110 freeway interchange

(Source: Google Map)

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105/110 freeway interchange

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Wasted Fuel and Wasted Time

- In 2016, Los Angeles tops the global ranking with 104 hour/commuter spent in traffic congestion
- In 2014, 3.1 billion gallons of energy were wasted worldwide due to traffic congestion
- In 2013, fuel waste and time lost in traffic congestion cost \$124 billion in the U.S.



(Source: La La Land)





Automated Vehicle Technology

• Definition of automated vehicles

At least some aspects of a safety-critical control function (e.g. , steering, acceleration, or braking) occur without direct driver input

• Sensing techniques

Radar, Lidar, GPS, odometry, computer vision, etc.





• Level of automation by SAE

- Level 0: No Automation
- Level 1: Driver Assistance
- Level 2: Partial Automation
- Level 3: Conditional Automation
- Level 4: High Automation
- Level 5: Full Automation



Connected Vehicle Technology

• Definition of connected vehicles

Vehicles that are equipped with Internet access, and usually also with a wireless local area network

- Communication flow
- Based primarily on dedicated short-range communications (DSRC)
- Between vehicles (V2V)
- Between vehicles and infrastructure (V2I/I2V)









Merging of Connectivity and Automation

Autonomous Vehicle Operates in isolation from other vehicles using internal sensors **Connected Automated Vehicle** Leverages autonomous and connected vehicle capabilities **Connected Vehicle** Communicates with nearby vehicles and infrastructure **U.S.** Department of Transportation **ITS Joint Program Office**





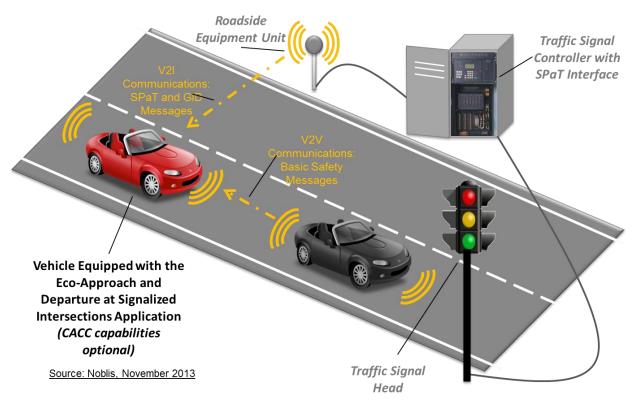
Eco-Approach and Departure

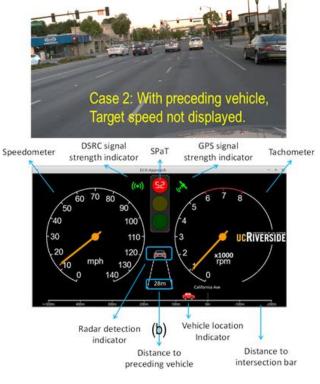




Eco-Approach and Departure

• Utilizes traffic signal phase and timing (SPaT) data to provide driver recommendations that encourage "green" approaches to signalized intersections



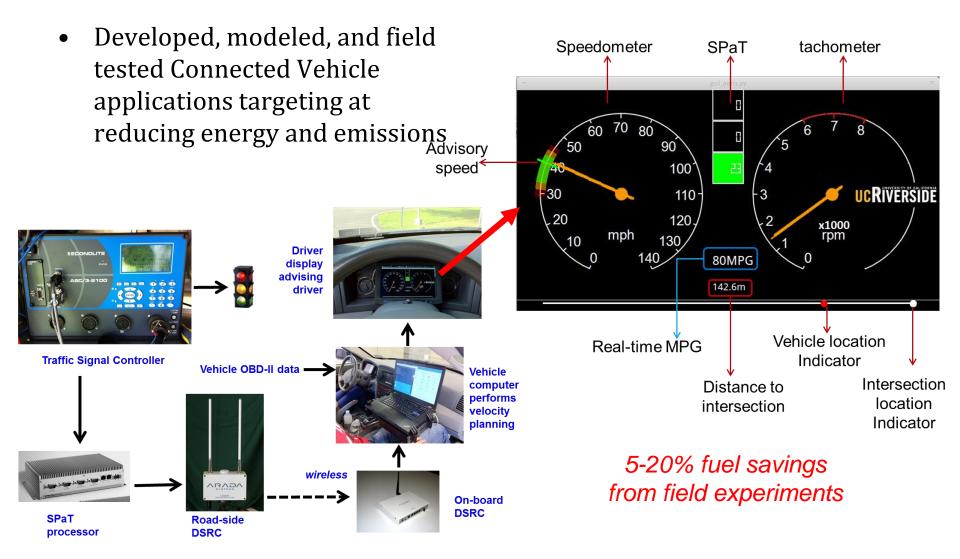


More benefits for fixed time control





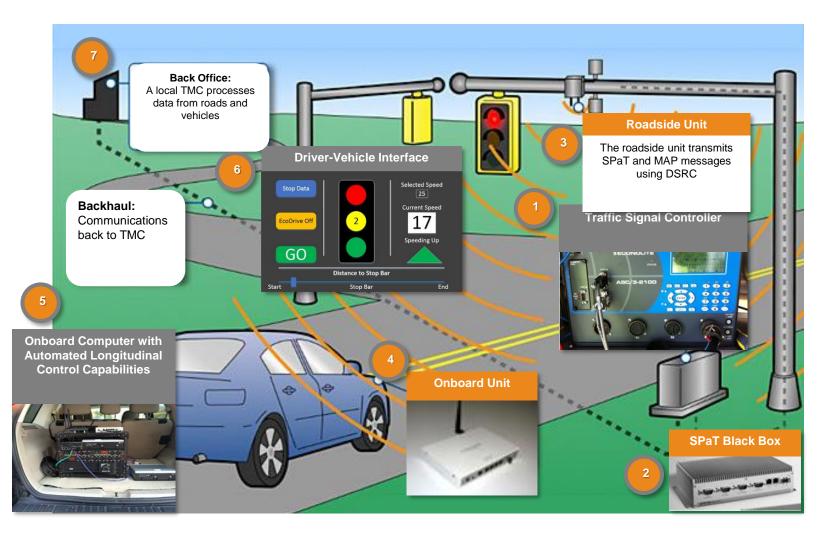
AERIS Connected Vehicle Research







GlidePath I: Partially Automated EAD





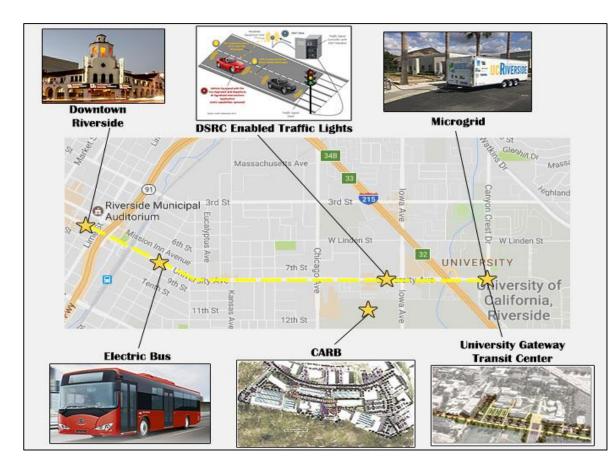








City of Riverside Innovation Corridor



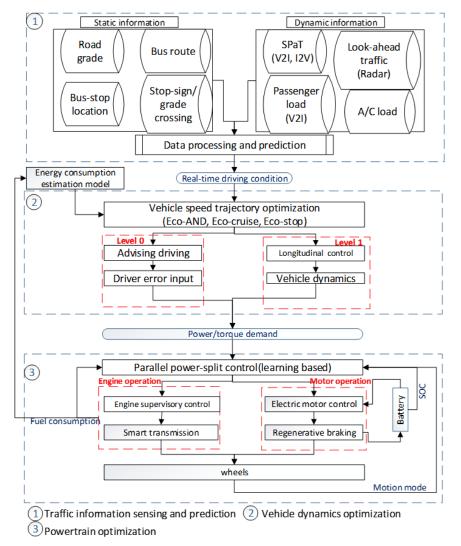
- Six mile section of University Avenue between UC Riverside and downtown Riverside
- All traffic signal controllers are being updated to be compatible with SAE connectivity standards
- UC Riverside is providing the Dedicated Short Range Communication modems in each traffic signal
- Corridor will be used for connected and automated vehicle experiments (ARPA-E hybrid bus, light-duty vehicles, etc.)



Connected Eco-Bus

- An Innovative Vehicle-Powertrain Eco-Operation System for Efficient Plug-In Hybrid Electric Buses
 - Co-optimization of vehicle dynamics and powertrain control
 - 20% energy consumption reduction target





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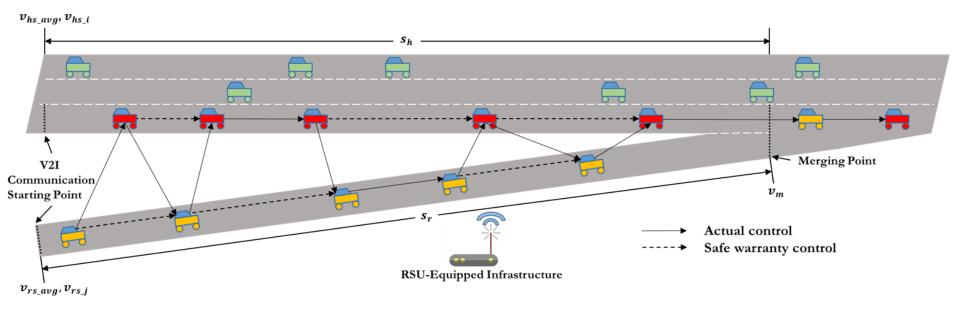
Cooperative Ramp Merging



Cooperative Ramp Merging

Benefits of *distributed consensus-based cooperative on-ramp merging system*

- Increase merging *safety* by applying V2X communications
- Increase traffic *mobility* by assigning vehicles into cooperative adaptive cruise control string before merging
- Reduce <u>energy</u> consumption by avoiding unnecessary speed changes

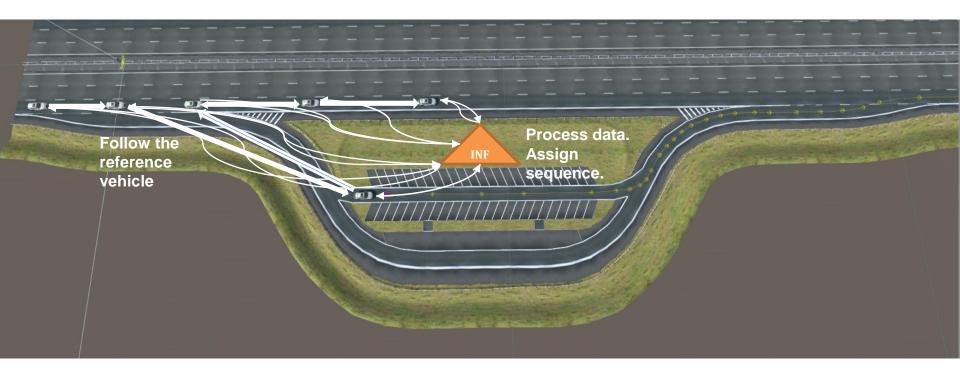


* RSU: Road Side Unit





System Workflow

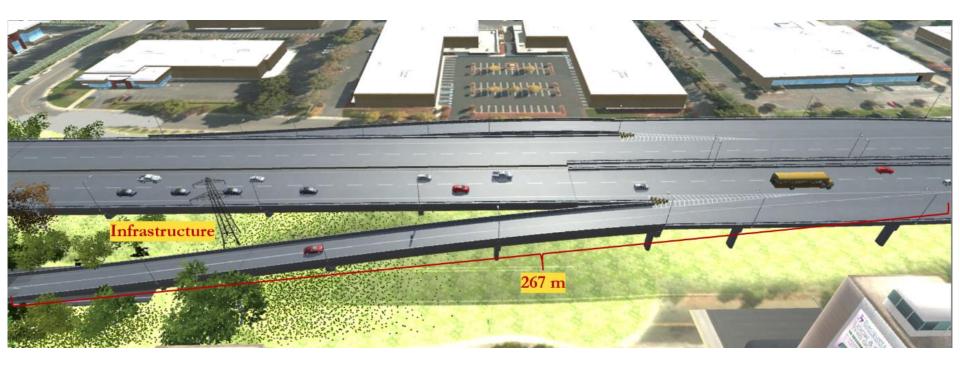






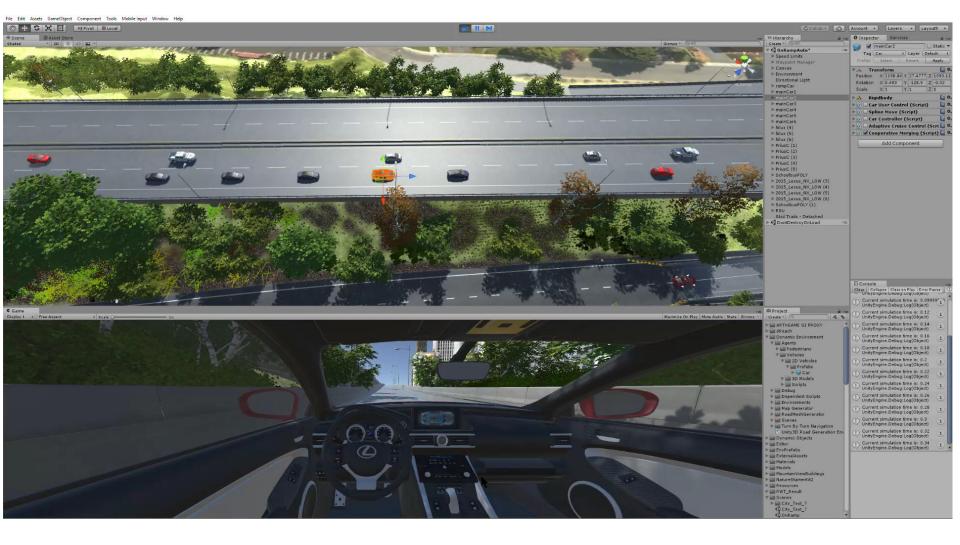
Simulation Setups

• Mountain View simulation network in game engine Unity3D











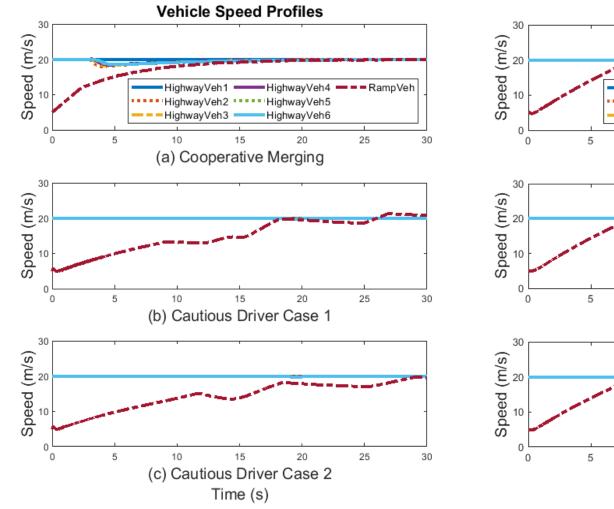


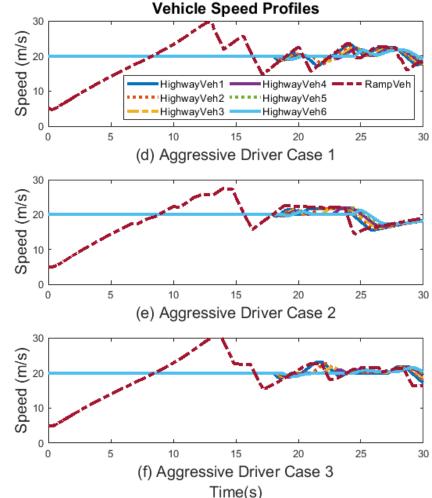
















	Travel Time	Energy	нс	со	CO2	NOx
Human-in-the-Loop (baseline)	233.58 s	9930.56 KJ	0.0200 g	2.8192 g	706.5392 g	0.0759 g
Cooperative Merging (proposed)	218.14 s	9153.97 KJ	0.0094 g	1.1737 g	651.287 g	0.0440 g
Reduction Percentage	7.08 %	8.48 %	112.77 %	140.20 %	8.48 %	72.5 %

* hydrocarbons (HC), carbon monoxide (CO), nitrogen oxides (NOx)

Savings in travel time, energy and emission



Thank you! Questions and comments? Contact info: Ziran Wang Email: zwang050@ucr.edu Website: www.me.ucr.edu/~zwang 100 Ba mate : 0:0:0.0